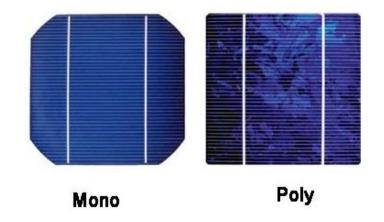
# Iterative Improvement Simulated Annealing





Slides based on lecture by Van Larhoven



#### **Iterative Improvement**

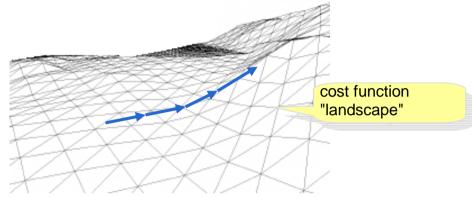
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## **Iterative Improvement**



General method to combinatorial optimization problems



#### Principle:

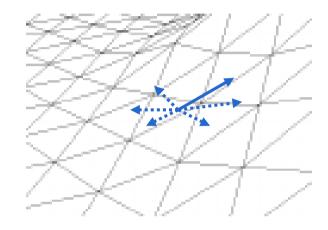
- Start with initial configuration
- Evaluate Gradient of some cost function (or fitness function)
- Go to direction of Gradient
- Stop if quality is sufficiently high, if no improvement can be found or after some fixed time

$$abla f(p) = egin{bmatrix} rac{\partial f}{\partial x_1}(p)\ dots\ rac{\partial f}{\partial x_n}(p)\ dots\ rac{\partial f}{\partial x_n}(p) \end{bmatrix}.$$

# **Iterative Improvement - without Gradient**



General method to solve combinatorial optimization problems



Principle:

- Start with initial configuration
- Randomly or systematically search neighborhood and select a most promising neighbor as candidate
- Evaluate some cost function (or fitness function) and accept candidate if "better"; if not, select another neighbor
- Stop if quality is sufficiently high, if no improvement can be found or after some fixed time

# **Iterative Improvement Prerequisites**



#### Needed are:

- A method to generate initial configuration
- A transition or generation function to find a neighbor as next candidate
- A cost function
- An Evaluation Criterion
- A Stop Criterion

# **Iterative Improvement Pros- and Cons**

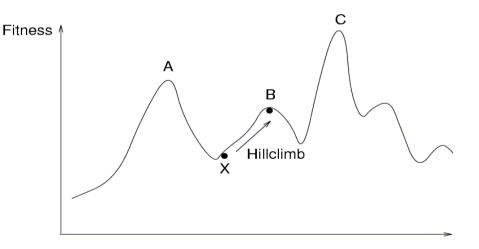


#### Simple Iterative Improvement or Hill Climbing:

- Candidate is always and only accepted if cost is lower (or fitness is higher) than current configuration
- Stop when no neighbor with lower cost (higher fitness) can be found

#### Disadvantages:

- Local optimum as best result
- Local optimum depends on initial configuration
- Generally no upper bound on iteration length



## How to cope with disadvantages



- Repeat algorithm many times with different initial configurations
- Use information gathered in previous runs
- Use a more complex Generation Function to jump out of local optimum

#### Use a more complex Evaluation Function:

- Do sometimes accept candidates with higher cost to escape from local optimum
- Adapt the parameters of this Evaluation Function during execution
- Based upon the analogy with the simulation of the annealing of solids



## Simulated Annealing

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# **Simulated Annealing**



Use a more complex Evaluation Function:

- Do sometimes accept candidates with higher cost to escape from local optimum
- Adapt the parameters of this Evaluation Function during execution
- Based upon the analogy with the simulation of the annealing of solids

#### Other Names

- Monte Carlo Annealing
- Statistical Cooling
- Probabilistic Hill Climbing
- Stochastic Relaxation
- Probabilistic Exchange Algorithm

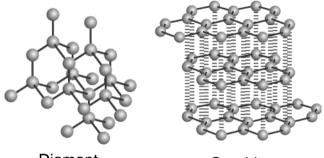
# Analogy



- Slowly cool down a heated solid, so that all particles arrange in the ground energy state -> e.g. crystal
- At each temperature wait until the solid reaches its thermal equilibrium
- Probability of being in a state with energy *E* :

 $P(\mathbf{E} = E_i) = \exp(-E/k_B * T*Z_{T0})$ 

- *E* Energy/Cost
- T Temperature
- *k*<sub>B</sub> Boltzmann constant
- $Z_{TO}$  Normalization factor (ev. temperature dependant)





Graphite

# Simulation of cooling (Metropolis 1953)



- At temperature *T* :
- Perturb (randomly) the current state to a new state
- $\blacksquare$   $\triangle E$  is the difference in energy between current and new state
- If  $\Delta E < 0$  (new state is lower), accept new state as current state
- If  $\Delta E > 0$ , accept new state with probability

 $P (accept) = exp (- \Delta E / k_B * Z_{T0} / T)$ 

- Eventually the systems evolves into thermal equilibrium at temperature T; then the formula mentioned before holds
- When equilibrium is reached, temperature T can be lowered and the process can be repeated

## **Simulated Annealing**



- Same algorithm can be used for combinatorial optimization problems:
- Energy E corresponds to the Cost function C
- Temperature T corresponds to control parameter t

 $P(\text{config} = \text{config}_i) = \exp(-\Delta C(i)^* K_{c0} / c)$ 

- C Cost
- *c* Temperature of Control parameter (slowly decreasing -> 0)
- $K_{c0}$  Normalization factor

chose so that there is a 50% initial chance

# **Algorithm**



```
initialize;
count = 0;
                          change configuration
bolzCount = 0;
                                                 change in cost
                          randomly
acceptCount = 0;
LOOP
     count++;
     perturb ( config.i \rightarrow config.j, \Delta C_{ij});
     IF \Delta C_{ij} < 0 THEN accept
     ELSE IF \Delta C_{ij} > 0 AND exp(-\Delta C_{ij}/c) > random[0,1] THEN
        accept; bolzCount++;
     IF accept THEN update(config.j); acceptCount++;
     measureProgress
     next lower (c)
END
```

# **Algorithm Termination/Acceptance**



For termination condition measure progress

e.g. count accepted transitions in 1000 iterations

```
measureProgress:
    IF count % 1000 == 0 THEN
        IF acceptCount == 0 BREAK
        ELSE bolzCount = 0; acceptCount = 0;
    END
```

#### **Parameters**



- Choose the start value of c so that in the beginning nearly all perturbations are accepted (exploration), but not too big to avoid long run times
- The function *next\_lower* in the homogeneous variant is generally a simple function to decrease *c*, e.g. a fixed part (80%) of current *c*
- At the end c is so small that only a very small number of the perturbations is accepted (exploitation)
- If possible, always try to remember explicitly the best solution found so far; the algorithm itself can leave its best solution and not find it again

## Performance



- SA is a general solution method that is easily applicable to a large number of problems
  - I "Tuning" of the parameters (initial c, decrement of c, stop criterion) is relatively easy
- Generally the quality of the results of SA is good, although it can take a lot of time
  - Results are generally not reproducible: another run can give a different result
- SA can leave an optimal solution and not find it again (so try to remember the best solution found so far)
- Proven to find the optimum under certain conditions; one of these conditions is that you must run forever



# All the other Algorithms

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#### **All the other Algorithms**



There are Thousands of other interesting algorithms:

https://en.wikipedia.org/wiki/Category:Algorithms

This was only an introduction





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